

This page is **Outdated**. Please follow new code in IPFN GIT Server Git <https://git.ipfn.tecnico.ulisboa.pt/tree/ISTTOK.git>

New ISTTOK EPICS Slow Control documentation moved to Markdown Format in [README.md](#)

TOC

New ISTTOK slow control system. 2

Intro. 2

Team and responsibilities 2

System description 3

 Temperature/Vacuum Node: Vacuum System 3

 Temperature/Vacuum Node: Temperature Sensors and ELCO Voltage Measurement Systems 3

 Central Node 4

State machine description 5

Hardware Platform 6

 Temperature/Vacuum Node 6

 Local Control 6

 Central Node. 6

Software Platform 6

 Temperature/Vacuum Node 6

 Local Control 7

 Central Node. 7

 Building EPICS base http://www.aps.anl.gov/epics/base/R3-14/12-docs/README.html#0_0_12 7

 Channel Access configuration 8

Protocol for communication between dspics and PC in ISTTOK slow control. 8

 Examples: PIC -> PC. 8

 PC -> PIC 8

 Table of words: 8

Archive System 8

References 8

Other pages:

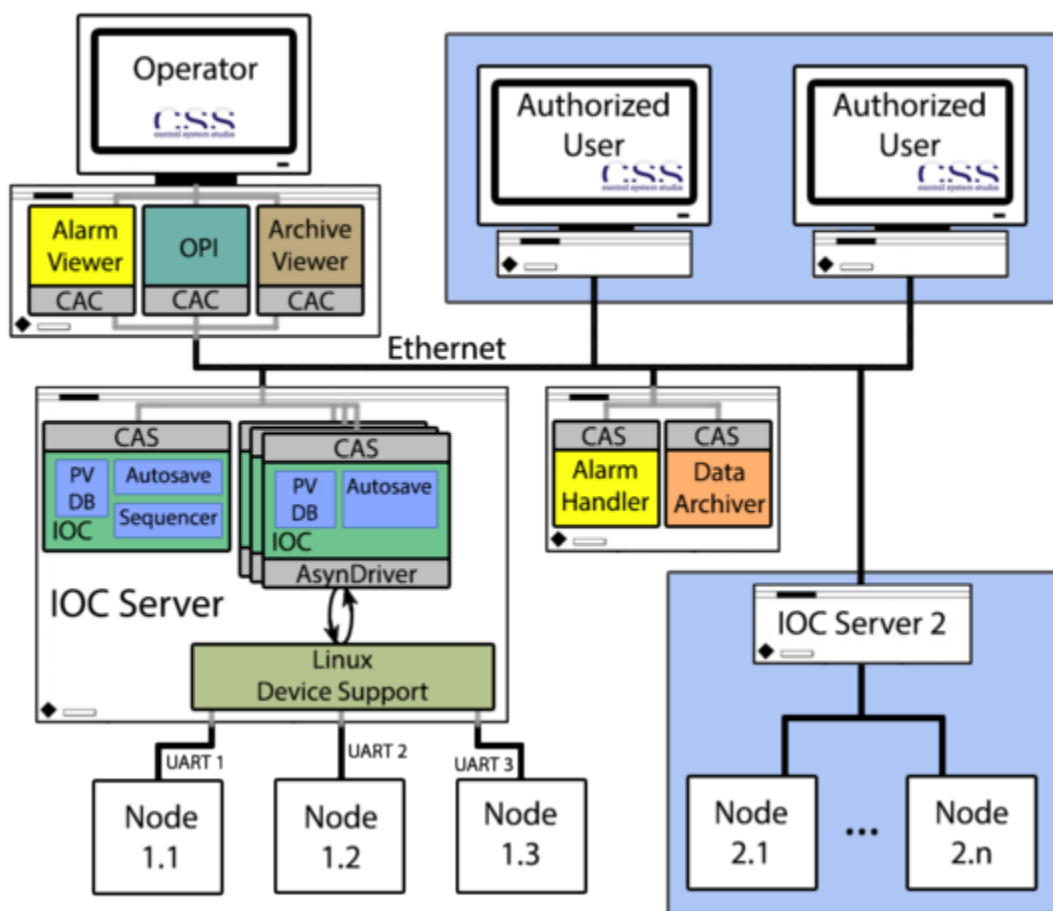
- [Archive](#)

New ISTTOK slow control system

Intro

The new ISTTOK slow control system is designed to replace the former vaccum/power/slow timing system based is the EDWARDS controller.

The new system uses the [EPICS framework](#) and the [Control System Studio](#), below there is a detailed description of the used software. In the next figure is depicted the system structure.



At the present all the software are installed in two IOC servers with the exception of the Control System Studio that is also used for the GUI management.

Team and responsibilities

- Horácio Fernandes (ISTTOK Leader)
- Bernardo Carvalho (Project Leader)
- Paulo Duarte (ISTTOK Session Leader, State Machine development)
- Tiago Pereira (dsPIC development, RS232 protocol/ Sensor Interface/ Wiring)
- Paulo F. Carvalho (Epics Applications)

- Bruno Santos (Epics)
- Gonçalo Quintal (Epics, CSS Gui Panels)

System description

Presently there are two instances of EPICS IOC Server implemented. One responsible for the Temperature /Vacuum Node. And a second one, installed in a Raspberry Pi, implemented in the new control unit launched at ISTTOK for the remote control of the vacuum pumps, named Central Node.

Temperature/Vacuum Node: Vacuum System

- Pfeiffer pressure gauges

The dsPic acquires the pressure value from the Pfeiffer gauge, with the Pfeiffer protocol working on RS485, and sends the pressure to a high level PC application.

Process Value in the IOC Server for this system.

PV Name	PV Type	Archive
ISTTOK:vacuum:Uptime	longin	no
ISTTOK:vacuum:Diff_Uptime	calc	no
ISTTOK:vacuum>Last_Uptime	calc	no
ISTTOK:vacuum:Pressure_Chamber1	ai	yes
ISTTOK:vacuum:Pressure_Primary1	ai	yes

Temperature/Vacuum Node: Temperature Sensors and ELCO Voltage Measurement Systems

- Thermocouple Sensor
- ELCO voltage measurement
- For communication was used a fiber optic

The dsPic uses the internal ADC to read the voltage signal from the thermocouple.

To measure the ELCO's voltage it was developed two boards one to read the ELCO's voltage and another to connect the fiber optic to dsPIC.

Process Value in the IOC Server for this system.

PV Name	PV Type	Archive
ISTTOK:temperature:Uptime	longin	no
ISTTOK:temperature:Diff_Uptime	calc	no
ISTTOK:temperature>Last_Uptime	calc	no

ISTTOK:temperature:RawTemperature_0	ai	yes
ISTTOK:temperature:Temperature_0	calc	yes
ISTTOK:temperature:RawTemperature_1	ai	no
ISTTOK:temperature:Temperature_1	calc	no
ISTTOK:temperature:RawTemperature_2	ai	no
ISTTOK:temperature:Temperature_2	calc	no
ISTTOK:temperature:RawTemperature_3	ai	no
ISTTOK:temperature:Temperature_3	calc	no
ISTTOK:temperature:RawCapbank_Voltage	ai	no
ISTTOK:temperature:Capbank_Voltage	calc	no

Central Node

- Pfeifer rotatory vacuum pump
- Edwards electro valve
- Seiko Seiki turbomolecular pump and control unit

There are: one control signal to turn the rotatory pump on and off; one control signal to open and close the Edwards electro valve; and four control signals, as well as four monitoring signals for the Seiko Seiki turbomolecular pump and control unit.

Process Value in the IOC Server for this system.

PV Name	PV Type	Archive
ISTTOK:central:RotatoryPump	bo	-
ISTTOK:central:RotatoryValve	bo	-
ISTTOK:central:TMPControllerOn	bo	-
ISTTOK:central:TMPControllerOnInv	calcout	-
ISTTOK:central:TMPControllerOff	bo	-
ISTTOK:central:TMPControllerOffInv	calcout	-
ISTTOK:central:TMPMotorOn	bo	-
ISTTOK:central:TMPMotorOnInv	calcout	-

ISTTOK:central:TMPMotorOff	bo	-
ISTTOK:central:TMPMotorOffInv	calcout	-
ISTTOK:central:Turbo_PW_Ind	bi	-
ISTTOK:central:Turbo_Emergency	bi	-
ISTTOK:central:Turbo_Acceleration	bi	-
ISTTOK:central:Turbo_NormalOperation	bi	-
ISTTOK:central:TMPManualValve	bo	-

State machine description

The developed state machine for EPICS uses the [State Notation Language and Sequencer](#) module.

This module implements a programming language specifically designed for programming *finite state machines* in such a way that it is easy for the program to interact with EPICS process variables (PVs), allowing to read and to write them and to react to changes in their value or status.

In the next Figure is depicted the state machine flow,

And the Process Value in the IOC Server for this system,

PV Name	PV Type	Archive
ISTTOK:central:AUTHORISATION	bo	-
ISTTOK:central:OPREQ	bo	-
ISTTOK:central:PROCESS-MODE	bo	-
ISTTOK:central:PROCESS-REQ	bo	-
ISTTOK:central:COUNTER	calc	-
ISTTOK:central:OPCALCSTATE	calc	-
ISTTOK:central:COUNTDOWN	mbbi	-
ISTTOK:central:PULSE-NUMBER	longout	-
ISTTOK:central:OPSTATE	longout	-
ISTTOK:central:CurrentTime	stringin	-

ISTTOK:central:TraceMessage	stringout	-
ISTTOK:central:STARTINGSTATE	mbbi	-
ISTTOK:central:STOPPINGSTATE	mbbi	-

Hardware Platform

Temperature/Vacuum Node

One PC Controller

- Intel(R) Atom(TM) CPU 330 @ 1.60GHz, Dual Core, 1 Gbyte RAM, 4 RAM
- 4 Serial Ports
- IP addr:192.168.1.152 (ISTTOK private network)
- Scientific Linux CERN 6 (SLC6) with MRG Realtime extensions
 - <http://linux.web.cern.ch/linux/scientific6/>
- Linux kernel 3.2.33-rt50.66.el6rt.x86_64
- NTP time conected to IPFN Gps NTP/PPS server IP:10.136.236.255

Local Control

One or more dsPic board running an embedded firmware

-

Central Node

- A Raspberry Pi, running a linux distribution
 - It also has a USB RS485 port for monitoring pressure (to be connected soon)
- An Interface Board, velleman k8000:
 - connected to raspberry Pi through I2C interface;
 - 8 isolated output connected to the relays (6 relays installed for the rotatory control, 2 in use);
 - 4 isolated outputs connected to SEIKO unit controller;
 - 4 isolated inputs connected to SEIKO unit controller;
- Indicator leds for the relays in the front panel
- 24 V power supply

Software Platform

All software stored in IPFN SVN server: <http://metis.ipfn.ist.utl.pt/svn/cdaq/ISTTOK/>

Temperature/Vacuum Node

EPICS v. 3.14.12.3 including modules:

- [asyn4-2](#)
- [seq-2.1.11](#)
- autosave-5-0

CS-STUDIO

- [CSS 3.1.4 Updated to CSS 3.2.16](#)
- BEAUTY - Archive system
- [Documentation](#)

Apache Tomcat

- [apache-tomcat-7.0.39](#)

Installed Scripts

- epicsenv.sh directory: /etc/profile.d/epicsenv.sh
- epicsenv directory: /usr/bin/epicsenv
- epicsEnv directory: /etc/opt/epics/env.d/epicsEnv
- epicsCaRepeater directory: /etc/init.c/epicsCaRepeater
- service-startup directory: /opt/epics/bin/services/service-startup
- epicsIocLogServer directory: /etc/init.c/epicsIocLogServer
- epicsenv directory: /usr/bin/epicsenv
- ioc-isttok directory: /etc/init.d/ioc-isttok
- isttok-archive-engine directory: /etc/init.d/isttok-archive-engine
- isttok-css-alarm-server directory: /etc/init.d/isttok-css-alarm-server

Local Control

Central Node

Linux Raspian "Stretch" (user :pi):

- IP addr:192.168.1.110 (ISTTOK private network)
 - NTP/timedatectl time conected to IPFN Gps NTP/PPS server IP:10.136.227.237 193.136.136.129
(this is mandatory, Rpi does not have a Real Time clock see <https://www.raspberrypi.org/forums/viewtopic.php?t=178763>)
- EPICS v. base-3.15.5 (in /usr/local/epics) including modules:

- synApps_5_8
 - asyn-4-26
 - seq-2-2-1
 - autosave-5-6-1
- IOC installed in '/opt/epics/iocs/'
For installation EPICS in Rpi see:

- <https://prjemian.github.io/epicspi/>

Building EPICS base http://wwwaps.anl.gov/epics/base/R3-14/12-docs/READMEhtml#0_0_12

Unpack file inside a folder named epics.

Set environment variables:

Run the perl script EpicsHostArch.pl in the base/startup directory to set EPICS_HOST_ARCH.

Do site-specific build configuration, site configuration:

configure/CONFIG_SITE Build choices. Specify target archs.
configure/CONFIG_SITE_ENV Environment variable defaults
configure/RELEASE TORNADO2 full path location

To build EPICS:

```
gnumake clean uninstall
gnumake
```

Create a symbolic link for the base folder of EPICS called base/ inside the folder epics.

Create a folder inside the epics folder named modules/.

Download asyn and snl modules and unpack them inside epics/modules/.

Create symbolic links for both unpack folders, asyn for the asyn module and seq for the snl module.

To build asyn:

Edit the config/RELEASE file and set the paths to your installation of EPICS_BASE (use the symbolic link base/).

Then run make on top level directory.

To build SNL:

Edit the configure/RELEASE file and set the paths to your installation of EPICS_BASE (use the symbolic link base/) and perhaps also configure/CONFIG_SITE.

Then run make on top level directory.

Note that make builds first in the configure directory, then the src tree, and finally the test and examples trees. A failure in the latter two will not impact your ability to write SNL programs.

Channel Access configuration

```
export EPICS_CA_ADDR_LIST=localhost
```

```
echo $EPICS_CA_ADDR_LIST, it should say localhost.
```

```
echo $EPICS_CA_SERVER_PORT, it should say 5064.
```

```
echo $EPICS_CA_REPEATER_PORT, it should say 5065.
```

This last values define ports used by EPICS and should be opened in firewall, iptable.

Protocol for communication between dspics and PC in ISTTOK slow control

- all bytes are readable ASCII
- all messages all terminated with two bytes: \r\n (13 10)
- messages have variable length
- framing character for fields inside message is space (32)
- individual fields inside each message have variable length
- the last three characters before the terminator are the ASCII representation of the checksum of all other bytes, excluding the terminator

Examples:

PIC -> PC

```
VL01_1 VL02_1 VL03_0 TE01_150.9 TE02_80.1 UP_7200 PR01_1.3e-4 CKS\r\n
```

PC -> PIC

```
VL01_1 CKS\r\n
```

Table of words:

VL - Valve

TE - Temperature

UP - Uptime

PRD - Wave Periode

PR - Pressure

Archive System

Main folder: /home/bernardo/css/

References

"EPICS IOC module development and implementation for the ISTTOK machine subsystem operation and control"

Paulo Carvalho, André Duarte, Tiago Pereira, Bernardo Carvalho, Jorge Sousa, Horácio Fernandes, Carlos Correia, Bruno Gonçalves, Carlos Varandas

Fusion Engineering and Design 86 (2011) 1085–1090